



Delta presents you with an ideal drive for door applications

Automation for a Changing World

## Delta Door Control Drive & Motor VFD-DD Series



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 **DELTA**  
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# Door Drive Functions and Features

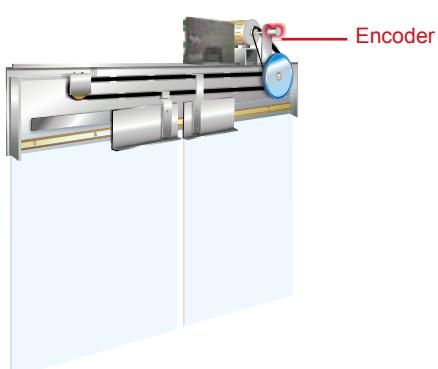
## ■ User Friendly Design



## ■ Door Control Solutions

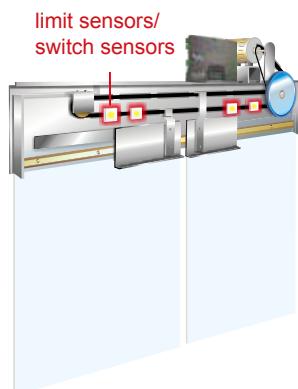
### ■ Distance Control Mode

For encoder applications this mode precisely controls the door's opening and closing position via encoder feedback signal.



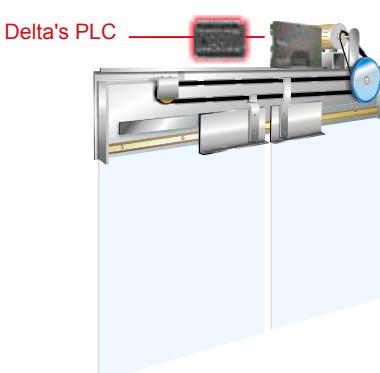
### ■ Speed Control Mode

For induction motor applications this mode executes door opening and closing via 2~4 limit sensors or switch sensors.



### ■ Multi-step Speed Control Mode

For PLC applications this mode uses Delta's PLC as a host controller to control door opening and closing in multi-step speeds.



## ■ Built-in Door Control Functions

### ▪ Door Width Auto-tuning

Door width is automatically measured and saved as the door opens and closes. It will open and close twice to confirm the door width accuracy. Once confirmed, the measurement is recorded into the drive parameters.

### ▪ Smooth Door Curve

The door will reopen in a reverse direction when door blockage is detected. The reopen is performed with a smooth curve to minimize the impact of vibration.

### ▪ Demo Mode

Demo mode demonstrates the door open, close and reverse motions to ensure the performance and quality of the drive system and the door structure.

### ▪ Asynchronous (IM) and Synchronous (PM) Motors Applications

Compatible with Delta ECMD series door control servo motor and other induction motors (signal type encoder that accepts open collector and differential signal with 5 or 12 V<sub>DC</sub>).

### ▪ Door Protection System

Passengers enter and exit the elevator with greater safety. When the light curtain and safety panel fail to function, the drive will command the door to re-open as it detects a rise of current caused by the blocked door.

### ▪ Blockage Detection

4 steps: 1. precise torque detection at blockage; 2. door remains at current position for a few seconds; 3. door "OPEN/CLOSE" time-out; 4. forced open.

### ▪ Built-in EMI Filters

(except for Basic Models)

## Specifications

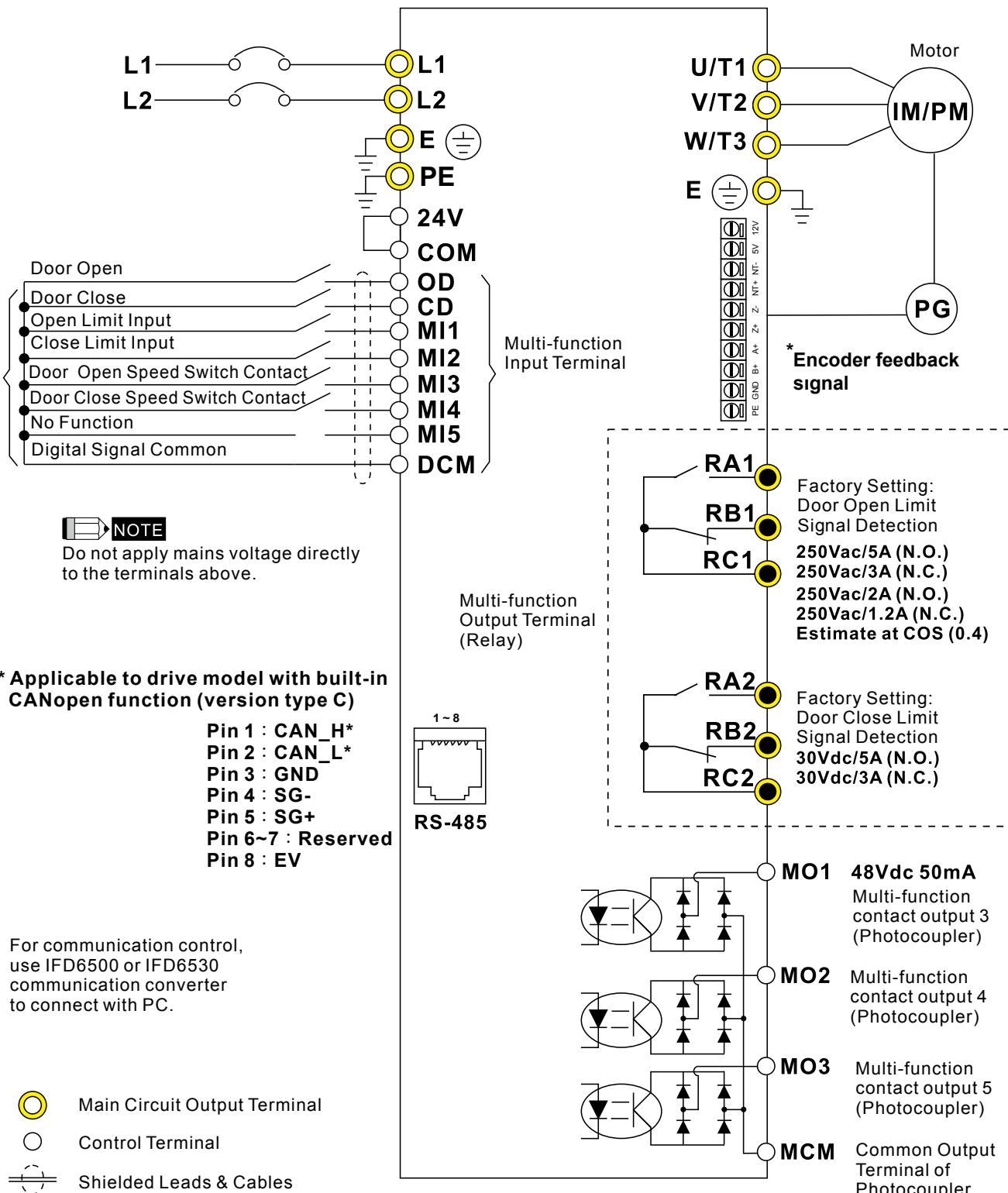
### 230V 1-phase: 200W and 400W models

230V 1-phase: 200W and 400W models		
Model Number VFD-__ _DD	002	004
Max. Applicable Motor Output (W)	200	400
Output Rating	Rated Output Capacity (KVA)	0.6
	Rated Output Current for Constant Torque (A)	1.5
	Maximum Output Voltage (V)	Proportional Input Voltage
	Output Frequency (Hz)	0.00 ~ 120.00Hz
	Carrier Frequency (kHz)	10 kHz
	Rated Input Current (A)	4.9A
Environment	Voltage Tolerance	Single Phase 200 -20% ~ 240V +10% (160~264V)
	Frequency Tolerance	50/60Hz ±5% (47 ~ 63Hz)
	Cooling Method	200W natural cooling / 400W natural cooling
	Frame	W170 * L215 * H55 mm

# General Specifications

Control Characteristics	<b>Starting Torque</b>	At 0.5Hz, starting torque reaches above 150% at 0.5Hz; under FOC+PG mode, starting torque reaches above 150% at 0Hz.			
	<b>Speed Control Range</b>	1:100 (external PG installation can achieve 1:1000)			
	<b>Speed Control Accuracy</b>	±0.5% (external PG installation can achieve 0.02%)			
	<b>Speed Response Ability</b>	5Hz (vector control can attain 30Hz)			
	<b>Max. Output Frequency (Hz)</b>	0.00 to 120.00 Hz			
	<b>Output Frequency Accuracy</b>	Digital command ±0.005%			
	<b>Frequency Setting Resolution</b>	Digital command ±0.01Hz			
	<b>Torque Limit</b>	200% torque current as maximum			
	<b>Accel/Decel Time</b>	0.00 ~ 600.00 sec			
Operating Characteristics	<b>V/F Curve Pattern</b>	Adjustable V/F curve of 4 independent points			
	<b>Frequency Setting Signal</b>	<table> <tr> <td><b>Keypad</b></td> <td>By parameter setting</td> </tr> <tr> <td><b>External Signal</b></td> <td>Multi-function input selection 1 ~ 5 (15 step speeds; JOG), parameter setting on serial communication port (RS-485)</td> </tr> </table>	<b>Keypad</b>	By parameter setting	<b>External Signal</b>
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<b>External Signal</b>	Multi-function input selection 1 ~ 5 (15 step speeds; JOG), parameter setting on serial communication port (RS-485)				
<b>Operation Setting Signal</b>	<table> <tr> <td><b>Keypad</b></td> <td>Set by RUN, STOP key</td> </tr> <tr> <td><b>External Signal</b></td> <td>2 wires (Fwd, Rev, RUN), JOG operation, RS-485 serial interface, demo mode</td> </tr> </table>	<b>Keypad</b>	Set by RUN, STOP key	<b>External Signal</b>	2 wires (Fwd, Rev, RUN), JOG operation, RS-485 serial interface, demo mode
<b>Keypad</b>	Set by RUN, STOP key				
<b>External Signal</b>	2 wires (Fwd, Rev, RUN), JOG operation, RS-485 serial interface, demo mode				
<b>Multi-Function Input Signal</b>	Multi-step speed selection MI1 ~ MI15, Jog, first to second accel/decel switches, demo mode, force stop, emergency stop, operation command source, parameter lock, driver reset, open/close limit signal, door open prohibited signal, force open signal, reposition, 2 <sup>nd</sup> step open/close curve selection				
<b>Multi-Function Output Signal</b>	(RC1,RA1,RB1), (RC2,RA2,RB2), (MO1,MO2,MO3 and MCM) AC drive operating, frequency attained, fault indication, over torque, over voltage, operation mode, alarm indication, demo mode indication, overheat alarm, drive is ready, emergency stop, braking signal, zero speed indication, PG indication error, position detection, limit signal, re-open/close indication, position finished				
<b>Communication Interface</b>	Built-in MODBUS, customize CAN Bus				
<b>Alarm Output Contact</b>	Contact "ON" when malfunctions occurs (relay with a "C" or "A" contact, or 2 open collector outputs)				
<b>Operation Function</b>	AVR, 4 set fault records, reverse inhibition, DC brake, auto torque/slip compensation, auto tuning, adjustable carrier frequency, output frequency upper and lower limits, parameter reset, vector control, MODBUS communication, abnormal reset, abnormal re-start, PG feedback control, fan control, demo mode, door width auto-tuning				
<b>Protection Function</b>	Over voltage, over current, under current, external fault, overload, ground fault, overload, overheating, electronic thermal, PG feedback error, external limit signal error, re-open/re-close				
Protection Characteristics	<b>Digital Keypad</b>	7 function keys, 4-digit 7-segment LED, 4 status LEDs, master frequency, output frequency, output current, custom units, parameter values for setup, review and faults, RUN, STOP, RESET, FWD/REV			
	<b>Built-in EMI filter</b>	Certified to EN55011 CLASS A			
	<b>Motor Protection</b>	Electronic thermal relay protection			
	<b>Over Current Protection</b>	The current forces 180% of the over-current protection and 240% of the rated current			
	<b>Overload Capacity</b>	150% for 120 seconds; 180% for 10 seconds			
	<b>Voltage Protection</b>	Over-voltage level: Vdc>400; low-voltage level: Vdc<200			
Environment	<b>Over-voltage Protection for Input Power</b>	Varistor (MOV)			
	<b>Overheat Protection</b>	Built-in temperature sensor			
	<b>Enclosure Rating</b>	IP20			
	<b>Operation Temperature</b>	-10°C ~ 40°C			
	<b>Ambient Temperature</b>	-20°C ~ 60°C			
	<b>Ambient Humidity</b>	Below 90% RH (non-condensing)			
	<b>Vibration</b>	1.0G less than 20Hz, 0.6G at 20 ~ 60 Hz			
	<b>Installation Location</b>	Altitude 1,000m or lower, keep from corrosive gasses, liquid and dust			
	<b>Certificate</b>				

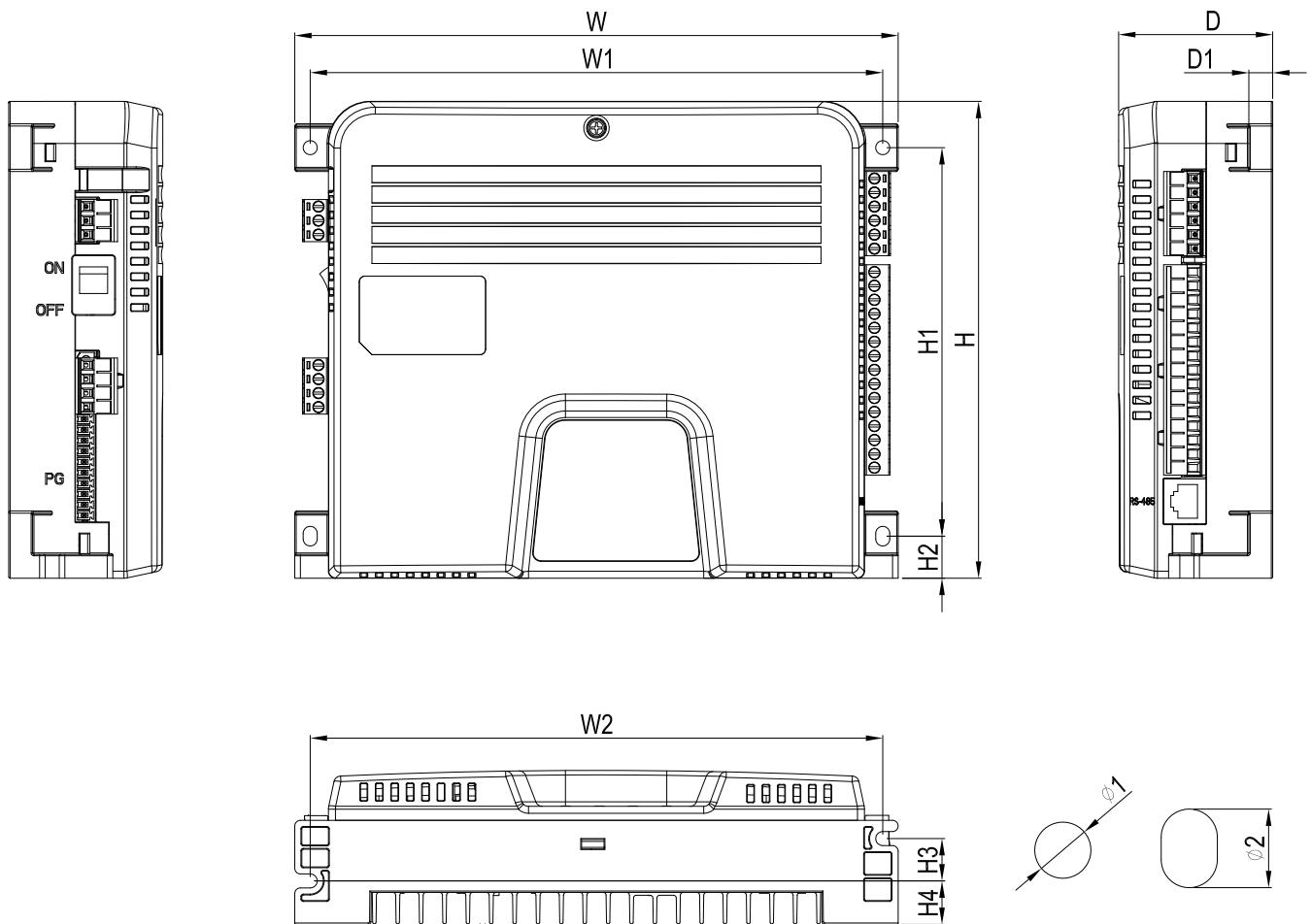
# Wiring



\*Please refer to VFD-DD series user manual for terminal definition of E type encoder.

# Dimensions

## FRAME\_A1




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### MODEL

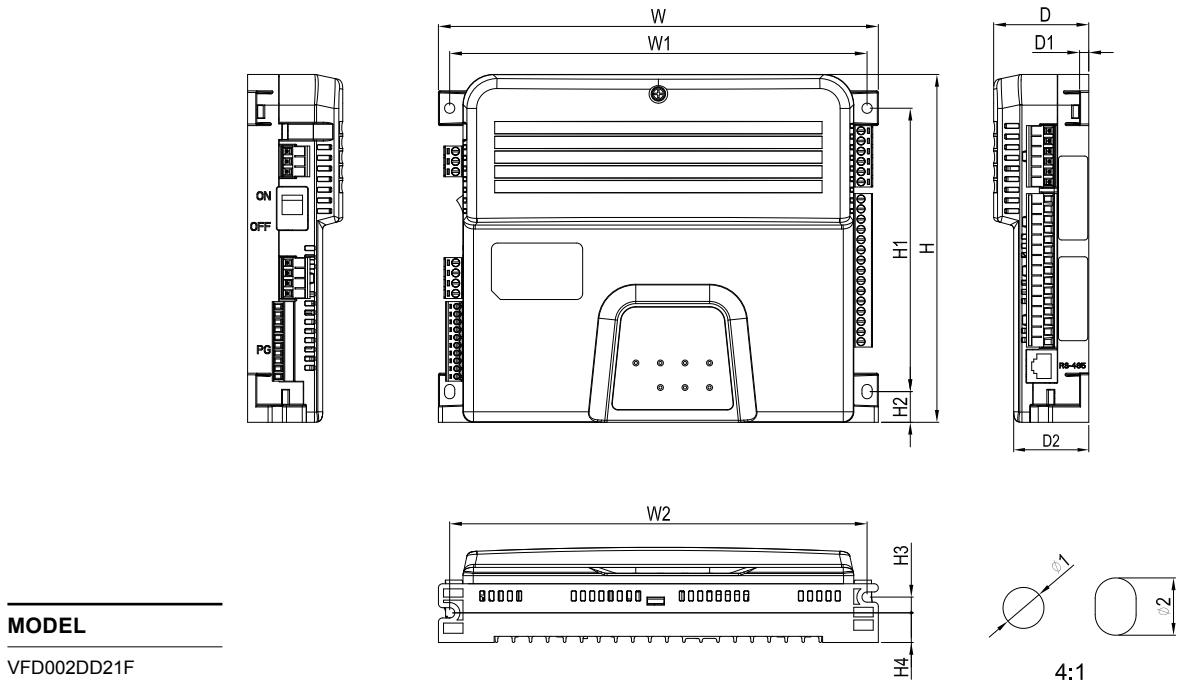
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VFD002DD21S  
 VFD002DD21V  
 VFD002DD21T  
 VFD004DD21S  
 VFD004DD21V  
 VFD004DD21T

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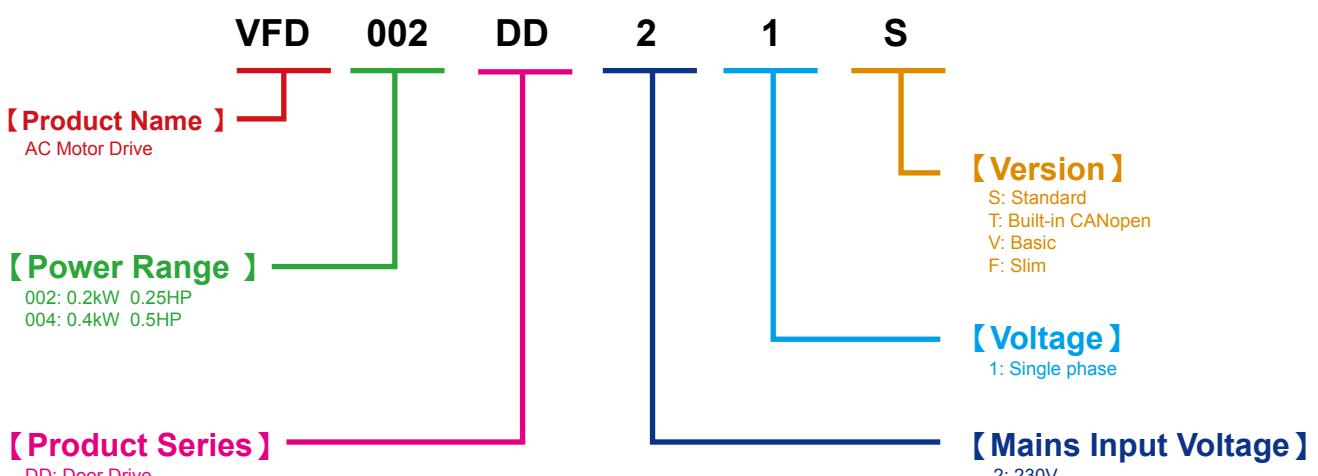
Frame	W	H	D	W1	W2	H1	H2	H3	H4	D1	Ø1	Ø2	
A1	mm	215.0	170.0	55.0	204.0	204.0	138.5	15.0	15.1	15.5	8.5	5.0	7.0
	inch	8.46	6.69	2.17	8.03	8.03	5.45	0.59	0.59	0.61	0.34	0.20	0.28

## FRAME\_A2



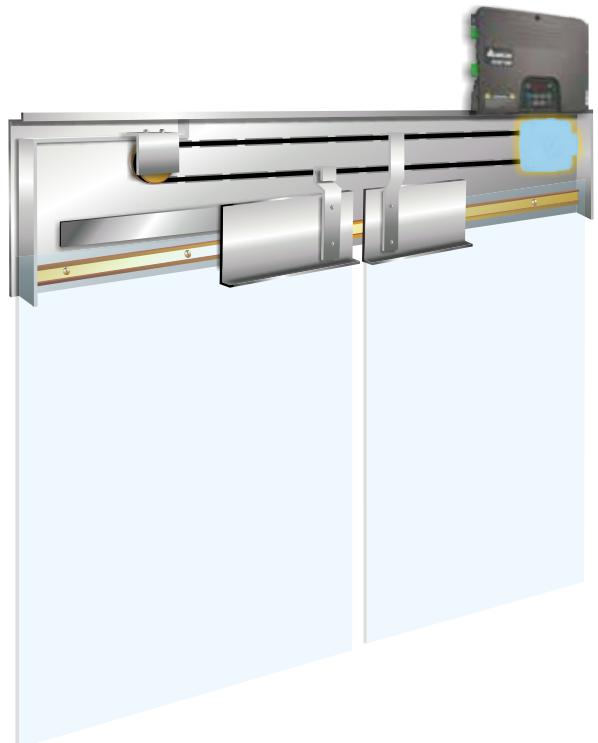
Frame		W	H	D	W1	W2	H1	H2	H3	H4	D1	Ø1	Ø2
A2	mm	215.0	170.0	46.5	204.0	204.0	138.5	15.0	7.7	14.5	4.5	5.0	7.0
	inch	8.46	6.69	1.83	8.03	8.03	5.45	0.59	0.3	0.57	0.17	0.20	0.28

## Model Name of Door Drive



## Servo Motors ECMD Series

- 55mm thin design
- Instant torque up to 5N·m
- Maximizes installation flexibility  
Both sides of motor can be installed
- Motor temperature detection and overheating protection

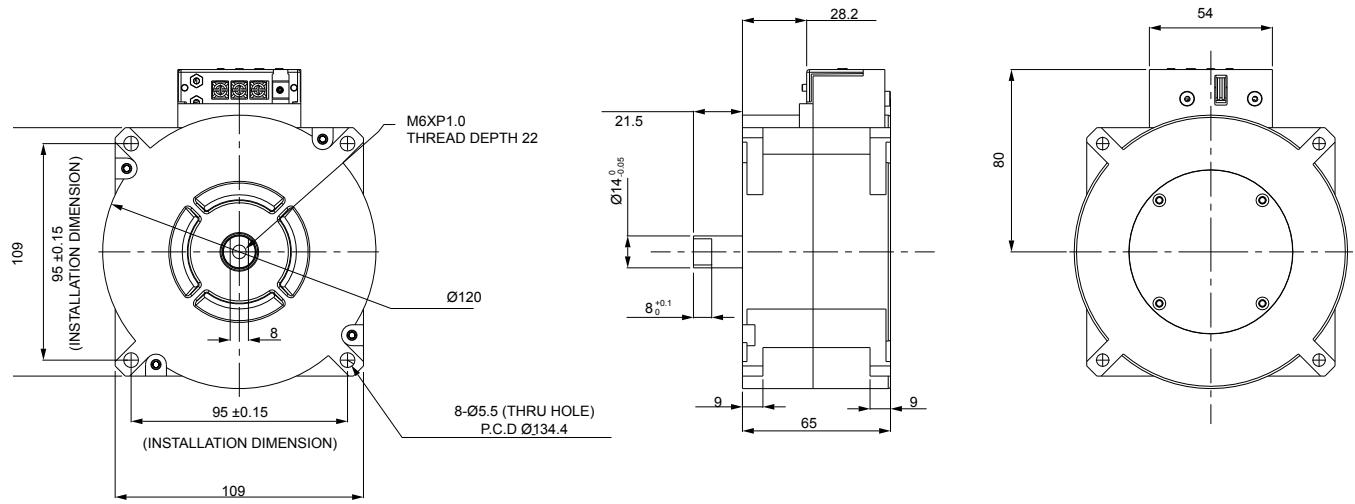


# Specifications

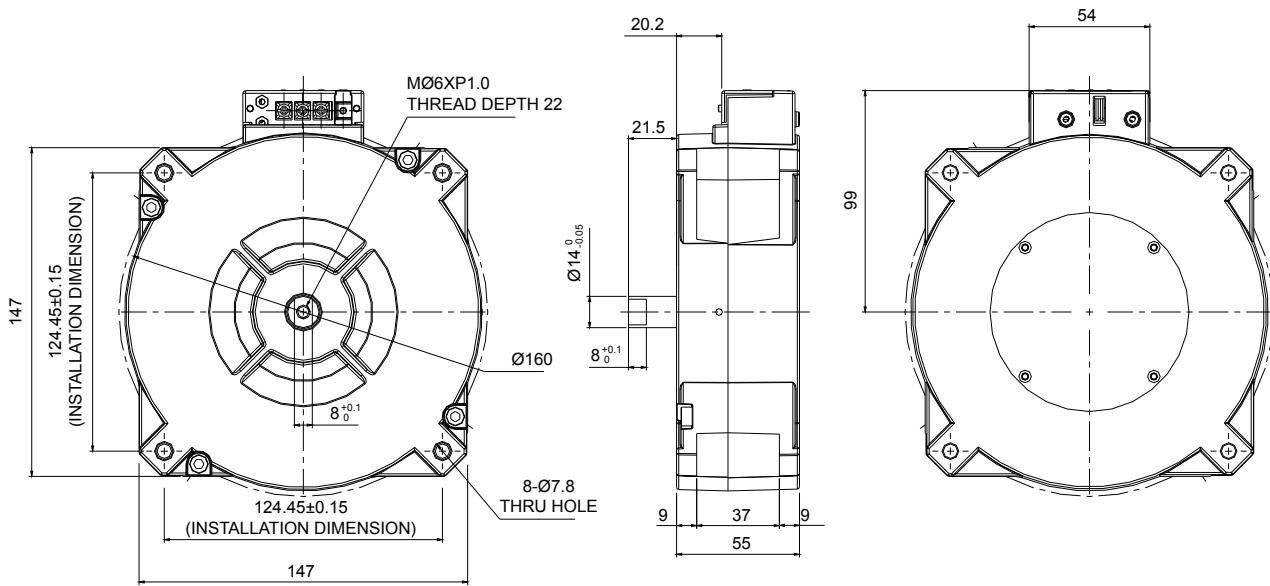
Model Name		ECMD-B91207M	ECMD-B91608M	ECMD-B81610M
Rated Speciation	<b>Rated Power (W)</b>	70	80	100
	<b>Rated Voltage (V)</b>	220	220	220
	<b>Rated Torque (N·m)</b>	2.0	3.0	3.5
	<b>Rated Speed (rpm)</b>	350	250	280
	<b>Rated Current (A)</b>	0.7	1.0	0.95
Rated Specification	<b>Pole Numbers</b>	10	16	16
	<b>Encoder Resolution</b>	10 bit (256ppr)	10 bit (256ppr)	12 bit (1024ppr)
	<b>Continuous Stall Torque (N·m)</b>	2.0	3.0	3.5
	<b>Max. Instant Torque (N·m)</b>	5.0	5.0	5.5
	<b>Max. Speed (rpm)</b>	750	600	500
	<b>Max. Instant Current (A)</b>	2.5	2.5	2.5
	<b>Rotor Moment of Inertia (Kg.m<sup>2</sup>)</b>	3.0X10 <sup>-4</sup>	4.9X10 <sup>-4</sup>	4.9X10 <sup>-4</sup>
	<b>Armature Resistance (Ohm)</b>	18.7	15.8	24.3
	<b>Armature Inductance (mH)</b>	195	177	273
	<b>Mechanical Time Constant (ms)</b>	1.96	2.42	2.13
	<b>Electrical Time Constant (ms)</b>	10.4	11.2	11.2
	<b>Insulation Class</b>	B		
	<b>Insulation Resistance</b>	10MΩ DC500V		
	<b>Insulation Strength</b>	1.5 k V <sub>AC</sub> , 1 min.		
Environment	<b>Max. Radial Shaft Load (N)</b>	98		
	<b>Max. Thrust Shaft Load (N)</b>	49		
	<b>Weight (kg)</b>	2.5	3.0	3.0
	<b>Maximum Winding Temperature</b>	130 °C		
	<b>Operating Temperature</b>	5 ~ 45 °C		
	<b>Storage Temperature</b>	-10 ~ 50 °C		
<b>Operating Humidity (%RH)</b>		20 ~ 95%RH (Non-condensing)		
<b>Storage Humidity (%RH)</b>		20 ~ 95%RH (Non-condensing)		
<b>IP Rating</b>		IP20 (Standard)		

## Dimensions

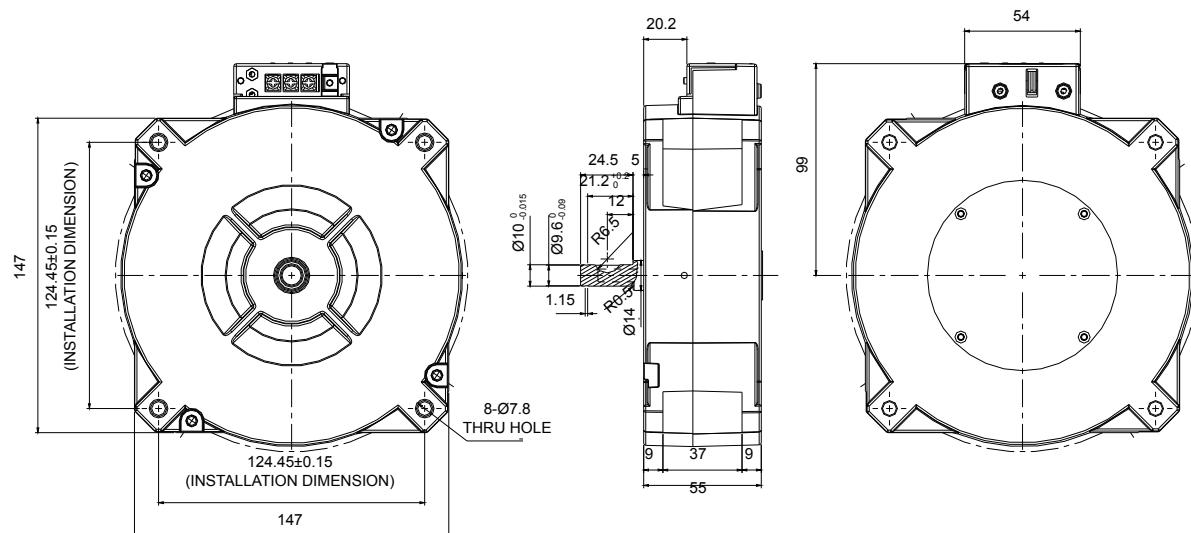
### ■ ECMD-B91207MS



### ■ ECMD-B91608MS/ECMD-B81610MS

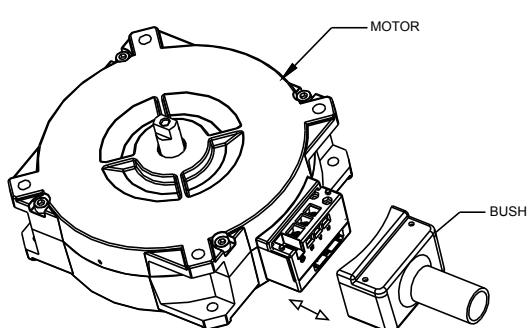


## ■ ECMD-B81610MG

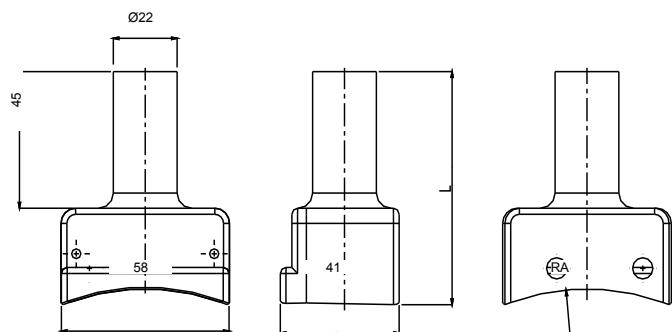


## ECMD Motor Dust Cap

### ■ ECMD Motor Dust Cap Installation



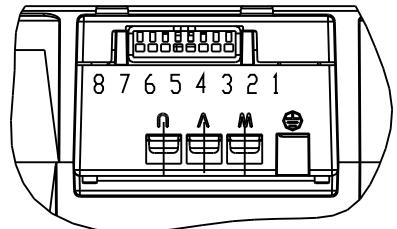
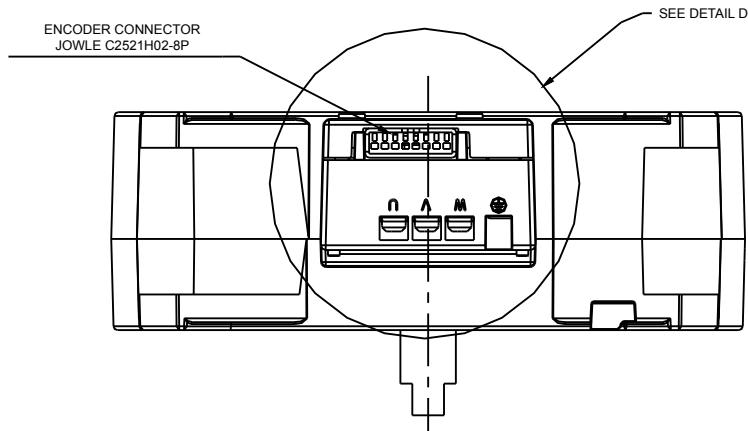
### ■ ECMD Motor Dust Cap Specification



MODEL NAME	L (mm)	RA (mm)	USED ON
DPB-N7860	77.4	60	ECMD-B91207M_
DPB-N7779	76.8	79	ECMD-B81610M_ ECMD-B91608M_

# Pin Definitions

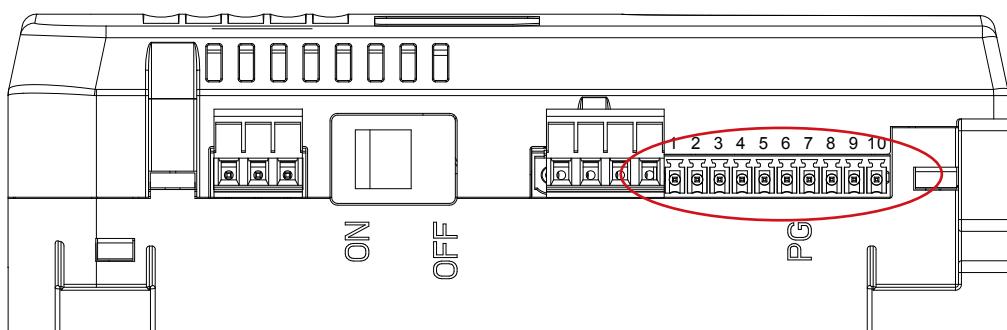
## ■ ECMD Motor Pin Definitions



PIN NO.	1	2	3	4	5	6	7	8
FUNCTION	A+	NTC+	B+	NTC-	PWM+	PWM-	+5V	GND

※ NTC+, NTC- function still under development.

## ■ VFD-DD Pin Definitions of Encoder Feedback Terminal



PIN NO.	1	2	3	4	5	6	7	8	9	10
FUNCTION	PE	G	B	A	Z	Z̄	+T*	-T*	5V	12V

※ +T, -T would be connected to pin NTC+, NTC- on the ECMD motor, keep it empty if the chosen motor does not support NTC function (motor overheat protection).

## ■ VFD-DD & ECMD

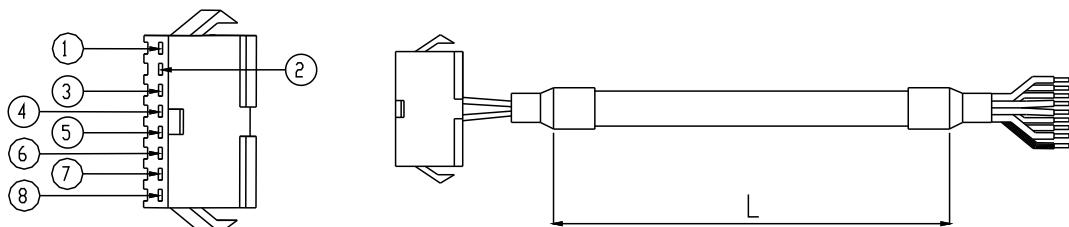
**Pin definitions and connection for the encoder feedback signal of motor**

Pin Definition of DD	Pin Definition of ECMD	Color of Core Wire
PE	--	--
G	GND	BLU
B	B+	WHT
A	A+	BLK
Z	PWM+	ORG
$\bar{Z}$	PWM-	ORG/RED
+T	NTC+*	BLK/RED
-T	NTC-*	WHT/RED
5V	+5VDC	BRN
12V	--	--

※ NTC+, NTC- functions are still under development.

## ■ ECMD Motor

**Pin Definitions and Signal Cable Specifications (Without D-SUB connector)**

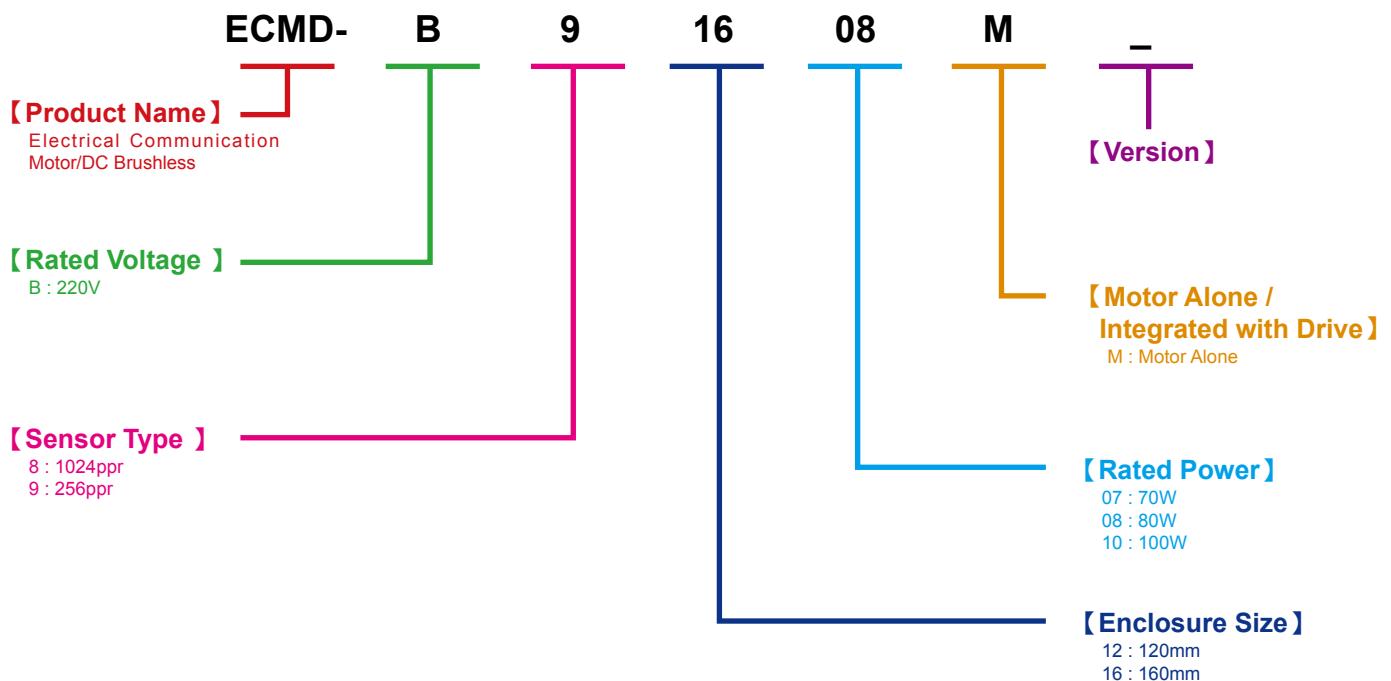


JOWLE C2522H02-8P DETAIL		
COLOR	DESCRIPTION	COLOR
1	A+	BLK
2	NTC+*	BLK/RED
3	B+	WHT
4	NTC-*	WHT/RED
5	PWM+	ORG
6	PWM-	ORG/RED
7	+5V	BRN
8	GND	BLUE

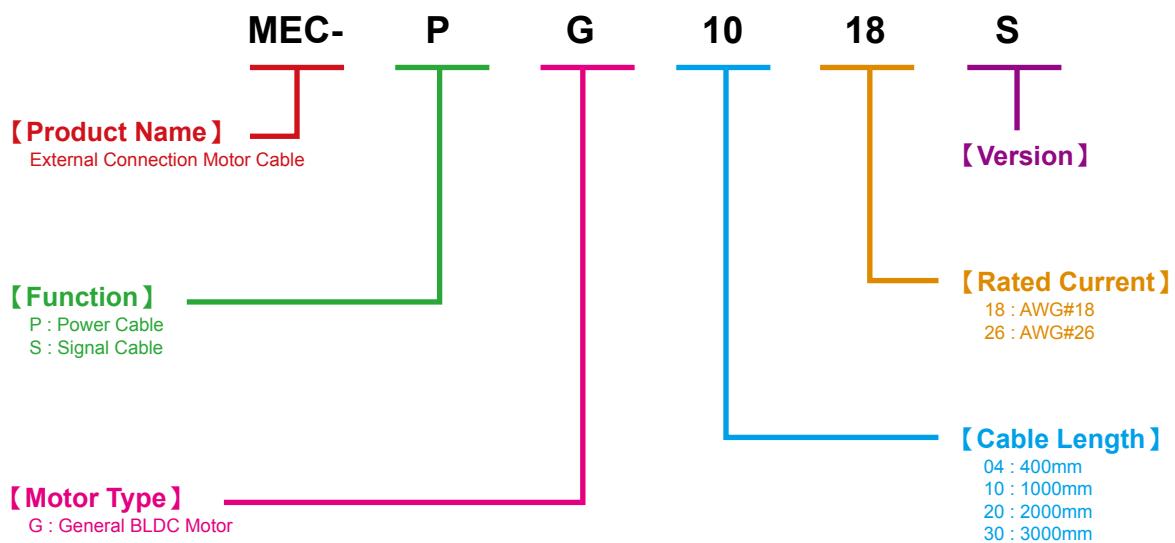
MODEL NAME	L (mm)
MEC-SG0426S	385
MEC-SG1026S	1000
MEC-SG2026S	2000
MEC-SG3026S	3000

\*NTC+, \*NTC- are under development, now are empty pins

## Model Name of ECMD Motor



## Model Name of Motor Cable



# Ordering Information

VFD-DD Series	Description
<b>VFD002DD21S</b>	230VAC-1Phase 200W AC motor drive, supports IM & PM motors, built-in EMI filter
<b>VFD004DD21S</b>	230VAC-1Phase 400W AC motor drive, supports IM & PM motors, built-in EMI filter
<b>VFD002DD21V</b>	230VAC-1Phase 200W AC motor drive, supports IM & PM motors
<b>VFD004DD21V</b>	230VAC-1Phase 400W AC motor drive, supports IM & PM motors
<b>VFD002DD21T</b>	230VAC-1Phase 200W AC motor drive, supports IM & PM motors, built-in EMI filter/CAN*
<b>VFD004DD21T</b>	230VAC-1Phase 400W AC motor drive, supports IM & PM motors, built-in EMI filter/CAN*
<b>VFD002DD21F</b>	230VAC-1Phase 200W motor drive, Supports IM&PM motors, built-in EMI Filter, slim type

\* CANopen protocol is provided upon request, please contact Industrial Automation Business Group

ECMD Motor	Description
<b>ECMD-B91207MS</b>	Servo motor enclosure size 120mm, rated power 70W, torque 2.0 N-m, speed 350 rpm
<b>ECMD-B91608MS</b>	Servo motor enclosure size 160mm, rated power 80W, torque 3.0 N-m, speed 250 rpm
<b>ECMD-B81610MS</b>	Servo motor enclosure size 160mm, rated power 100W, torque 3.5 N-m, speed 280 rpm
<b>ECMD-B81610MG</b>	Servo motor enclosure size 160mm, rated power 100W, torque 3.5 N-m, speed 280 rpm (different shaft shape)

\* Without power cable and encoder cable

Accessories	Description
<b>MEC-SG0426S</b>	385mm ECMD motor encoder cable, without D-SUB connector
<b>MEC-SG1026S</b>	1,000mm ECMD motor encoder cable, without D-SUB connector
<b>MEC-SG2026S</b>	2,000mm ECMD motor encoder cable, without D-SUB connector
<b>MEC-SG3026S</b>	3,000mm ECMD motor encoder cable, without D-SUB connector
<b>MEC-PG0418S</b>	370mm ECMD motor power cable
<b>MEC-PG1018S</b>	1,000mm ECMD motor power cable
<b>MEC-PG2018S</b>	2,000mm ECMD motor power cable
<b>MEC-PG3018S</b>	3,000mm ECMD motor power cable
<b>DPB-N7860</b>	ECMD-B91207MS dust cap
<b>DPB-N7779</b>	ECMD-B91608M/_ECMD-B81610M_dust cap



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